Standard Package Motion Controller General Purpose OPEN Motion Controller

TECHNO OPEN-Motion Controller has NC technology and Rich Motion Functions. This controller is easily implemented. For general purpose, we have Standard Packages which are suit for winding, cutting, robot and/or electric-cam. For more special applications, we customize our software in order to provide a type of operation you may request.

The applications described bellow are common in Precise Cutting Pack, Winding Pack, Robot Pack, and Electric Cam Pack.

■ TECHNO Standard Operation Software You can use general PC software to operate all functions of OPEN-MC.

Stand-alone Operation OPEN-MC is a stand-alone system so that it is independent on PC.

Standard Input/Output Control

OPEN-MC has the general i/o control and you can connect the operation panel for auto/manual operation.

TECHNO code and G code

Screen of Standard Operation Software
Operation Panel (option)

 Image: Image:

Customers can easily determines the type of operations such as transferring, precise cutting or welding by G code and/or TECHNO code without consulting the special knowledge for servo-control.

• ex. TECHNO code instructions

Eight lines described bellow command the following operations: 4-positioning, 2-judgment of input, 2-output control, timer and call of subroutine

<u>2-output control, timer al</u>						
TECHNO CODE	DESCRIPTION					
①PTPA XO YO ;	move to org. (0, 0) from any position	ΥI				
(2)PTPA X1000 Y500 WR01 ONR01;	input01 : on \rightarrow stop	1000	5 Move and	d pause ——	->.	
	input01 : off \rightarrow move to (1000, 500)	1000	⑥ Output 0	5/01: off	1	
(3)TIMO. 5 ;	Pause 0.5sec.		_		5 PTPA	
(4)CALL SUB1 JNR02 ;	Input02:ON \rightarrow CALL SUB1		Pause	e 0.5sec		
	Input02 : OFF \rightarrow pass to next	500	_			
(5)PTPA X#1000 Y#1001 TIM1.0;	move to (X, Y) and pause for a total of		② Judge of			
	1 sec	(1)	Input 01	④ Input 02:0	ON,	
60FR05 0FR01 ;	output05/01=off	4	PTP		inouon .	Y
(7end ;	Program END		500	1000	1500	^
SUB1 :	subroutine label	17				
(8)CIRR X0 Y0 I100 J0 F1000;	circle motion	(Î)	Origin(0,0)			
FND ·	subroutine END	U				

Rich Motion Functions

- High Level Servo Technology for a multi axes machine like a NC/Robot
- Rich Option Functions for various precise machines and special motions: direct NC, macro, multitask, automatic corner override, S-curve acceleration /deceleration manual pulse generator, spindle control, parallel axes, synchronization control, electric cam, torque-control, lathe, thread-cutting, position sensing, rigid tapping, tangent-control

Operation by original application software & Merit of Open Software Interface (IF) Software IF is open so that EXCEL or general software is allowed to operate OPEN-MC directly.



TB04-2375eng.jtdc-1